

ctools - Feature #3003

In-memory access for ctskymap significance map from Python

09/13/2019 01:36 PM - Tibaldo Luigi

Status:	Rejected	Start date:	09/13/2019
Priority:	Normal	Due date:	
Assigned To:		% Done:	0%
Category:		Estimated time:	0.00 hour
Target version:			
Description			
I do not think the significance map (as well background, acceptance) are exposed in the Python interface of ctskymap to make it possible to use them in memory. This could be a useful feature.			

History

#1 - 09/13/2019 03:28 PM - Knödlseider Jürgen

- Status changed from *New* to *Feedback*

The ctskymap::fits() method allows to access these maps.

#2 - 09/13/2019 04:06 PM - Tibaldo Luigi

I don't seem to be able to access the fits method from Python. Could you please provide an example snippet?

#3 - 09/15/2019 09:12 PM - Knödlseider Jürgen

Which version of the code are you using? The feature was only added very recently.

#4 - 09/30/2019 12:26 PM - Knödlseider Jürgen

- Status changed from *Feedback* to *Rejected*