

ctools - Feature #3003

In-memory access for ctskymap significance map from Python

09/13/2019 01:36 PM - Tibaldo Luigi

<b>Status:</b>	Rejected	<b>Start date:</b>	09/13/2019
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assigned To:</b>		<b>% Done:</b>	0%
<b>Category:</b>		<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			
I do not think the significance map (as well background, acceptance) are exposed in the Python interface of ctskymap to make it possible to use them in memory. This could be a useful feature.			

History

#1 - 09/13/2019 03:28 PM - Knödlseider Jürgen

- Status changed from New to Feedback

The ctskymap::fits() method allows to access these maps.

#2 - 09/13/2019 04:06 PM - Tibaldo Luigi

I don't seem to be able to access the fits method from Python. Could you please provide an example snippet?

#3 - 09/15/2019 09:12 PM - Knödlseider Jürgen

Which version of the code are you using? The feature was only added very recently.

#4 - 09/30/2019 12:26 PM - Knödlseider Jürgen

- Status changed from Feedback to Rejected